

# Agricola Wind Magnetic Well Survey Final Report

Cayuga County, NY

Prepared by UAV Exploration Inc.

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#### INTRODUCTION

This report describes a Magnetic Orphaned/ Plugged & Abandoned Well Survey carried out by UAV Exploration (UAVEX) in May 2024 as part of the Agricola Wind Project in Cayuga County, NY. The project goal was to identify and locate orphaned, plugged and abandoned (P&A) and potential unknown steel-cased Oil and Gas (O&G) wells within the project area.

#### **PROJECT AREA**

The project/ survey area of operations (AOI) consists of an approximately 2,629 acre network of proposed wind turbine locations and collection corridors near Venice Center, NY.

The project area can be described as moderate rolling terrain with elevation changes of approximately 100-115 meters across the AOI. The area has a mixture of light woods, agricultural farm fields, residential housing, farms, country and state roads, as well as power lines and sparce towers.

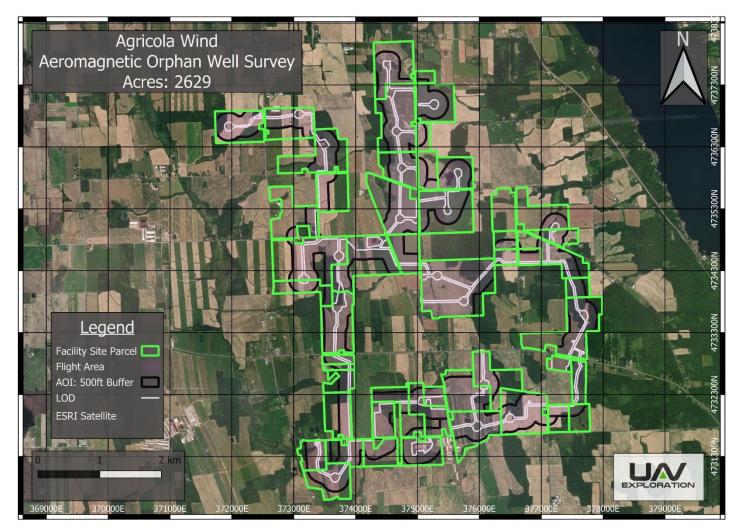


Figure 1: Project Area

#### **GEOPHYSICAL SURVEY METHODOLOGY**

The survey called for a multi-phase approach to collect, process, interpret, and confirm magnetic data to locate potential steel-cased wells in the project AOI. These primary phases were Flight Operations, Data Processing and Interpretation, and Ground Truthing.

The principal geophysical sensors used included an Ex-Mag atomic magnetometer system mounted on an Unmanned Aerial System (UAS) platform, a Gem Systems GSM-19 Overhauser Proton Procession magnetometer base station and Schondstedt handheld magnetic locators.

## FLIGHT OPERATIONS

UAVEX flight crews go to great lengths to conduct aerial data with the utmost precision. Strict quality control of flight operations is paramount to locating subtle and weak anomalies, eliminating false positives, and producing the most accurate and aesthetically pleasing deliverables. Flight crews perform aerial data collection only when conditions are ideal; refraining from operations during periods of moderate to high winds and/or high thermal activity or during high solar activity, all of which can negatively impact data quality.

The survey AOI was established and divided into subsections consisting of areas of manageable size and shape to allow the UAS field crews to perform the aerial surveying efficiently while complying with line of sight (LOS) requirements and other safety related standard operating procedures. Each subsection's boundaries were defined according to best practices with the necessary overlaps between individual flight missions. All flights were planned and executed at the lowest, safest, nominal draped altitude above ground level (AGL) utilizing a 1-meter Digital Terrain Model (DTM) while considering on site conditions and maximum tree height within the AOI. The nominal altitude selected for this project was 38 Meters AGL (sensor height). Nominal line-spacing was 30 meters.

Each survey day began with a thorough pre-flight and safety briefing, including checking FAA notices to airmen, airspace restrictions, temporary flight restrictions, weather, obstacles, and monitoring space weather. UAS flights were operated within FAR Part 107 guidelines by an FAA certified pilot holding a valid commercial UAS pilot certificate and visual observer flight crew.

At the start of aerial survey operations, the GSM-19W Overhauser Base Station was set up and initiated at a magnetically quiet location with a logging rate of .33 Hz.

Takeoffs were performed manually by the pilot and the pre-programed survey lines were flown by autonomous lateral and vertical navigation. Landings were conducted manually by the UAS pilot and ground crew.

The position and altitude of the aircraft and magnetometer payload was achieved using a combination of Barometric Pressure Measurement, GPS, Compass, Inertial Measurement Unit (IMU) and RADAR altimeter. AGL altitude was maintained using a combination of RADAR altitude measurement and barometric pressure readings. Barometric pressure and altitude corrections were maintained during flight operations using a stationary barometric base station.

The magnetometer was suspended from the UAS in a fixed orientation by a proprietary vibration isolated mounting and stowing system at a sensor distance of approximately 1.3 meters to reduce UAV noise and magnetic interference. Nominal survey speed was maintained at 6-10 meters per second ground speed to achieve optimal and consistent pitch attitude.

Scan rates for data acquisition were 1000 Hertz (Hz) for the magnetometer and 5 Hz for GPS positioning which translates to an effective downline sampling of 6mm – 10mm.

Raw survey data was downloaded at the completion of each flight and quality checked before proceeding to the next survey area. The total combined survey distance for the project was approximately 432 line-kilometers.

## **UAS AIRCRAFT**

The primary unmanned aircraft systems (UAS) used was a UAVEX Explorer-3 UAS Hexacopter, custom manufactured by UAV Exploration in the US. The platform has a maximum takeoff weight of 55lbs and contains various onboard systems specifically developed for use in geophysical surveys while providing the highest level of safety possible. Some of the aircraft's features are: Terrain following RADAR, Triple redundant IMUs, Barometers, and Compass Systems. Dual GPS system, dual battery systems and redundant power management systems. The aircraft has 6 propulsion motors which provide stable flight characteristics and can maintain flight in the event of a motor failure. The aircraft also has emergency features such as autonomous return to home, autoland, and battery and communications failsafes.

## AIRBORNE MAGNETOMETER SYSTEM

The magnetometer system used was a custom ExMag Atomic Magnetometer System. The onboard sensor package is centered around a Geometrics Micro Fabricated Atomic Magnetometer (MFAM) system. It is a dual sensor, 1000 Hz logging rate device with onboard logging, GPS and telemetry capabilities. Specifications listed below.

Operating Principle: Laser pumped cesium vapor (Cs133 non-radioactive) dual-sensor, total field scalar magnetometer with onboard IMU.

Operating Range: 20,000 to 100,000 nT.

Gradient Tolerance: 10,000nT/m.

Noise/Sensitivity: 0.005nT/ Hzrms typical.

Sample Rate: 1000 Hz. synchronized to GPS 1PPS.

Bandwidth: 400Hz.

Heading Error: ± 5 nT over entire 360° equatorial and polar spins typical.

Telemetry Output: 900 MHz

GPS: Commercial grade with typical 1 m accuracy.

### **MAGNETIC BASE STATION**

Recording of diurnal magnetic variation was performed using a Gem Systems GSM-19W Overhauser base station magnetometer. This system was set up each day prior to aeromagnetic surveying in the same location for the duration of the project. The sample rate was 0.33 Hz. This base station, as well as the drone-mounted magnetometer, are time synchronized to UTC+0 time using each systems' integrated GPS unit. This common time index was used to align the diurnal magnetic trends in time to the aeromagnetic data for removal/ correction.

## DATA PROCESSING

For each mission dataset, raw data files were batch processed into a single comma-delimited file using custom software. The concatenated files from each mission were imported into Oasis Montaj for all remaining processing.

The major processing steps include:

- Instrument Lag
- Removal of magnetic heading error
- Removal of diurnal variation using base station data
- 1D filtering to remove 60 Hz AC power interference.
- Magnetic attitude correction of noise due to wind / motion
- 2D data gridding using the Minimum Curvature gridding algorithm.
- Leveling and combining sorties into one dataset
- Vertical derivative convolution 2D grid filter
- Analytic signal 2D grid filter
- Other 2D smoothing filters

## TARGET SELECTION

At the completion of processing for each survey grid sub-section, data was analyzed and a comprehensive list of targets of interest (also known as anomalies of interest) was compiled for further field investigation along with their respective latitude and longitude positions.

A variety of methods are used to determine if a target has the possibility to be a sub-surface O&G well. The initial process begins with reconciling targets with georeferenced aerial imagery and video to eliminate visible anomalous signatures such as housing, commercial structures, steel infrastructure, agriculture, utilities and other discernable ferromagnetic features. Due to the varied magnetic response generated by wells, many initial targets are selected for investigation and reconciled one-by-one until only potential well-like anomalies remain. All un-reconciled targets were investigated during the ground truthing survey.

## **GROUND TRUTHING SURVEY**

For the ground survey the field crew traversed on foot to each anomaly location individually for ground identification and magnetic verification. Sub-surface targets that presented as a potential well based on the aerial and ground-based magnetic response were ground surveyed by:

(1) The peak aerial detection location was first flagged using the GNSS system.

(2) Using the magnetic locator systems, a serpentine path was walked within an approximate 20meter diameter radius, starting at the center.

(3) Once the potential target source was detected, a circular survey was conducted around the target to determine if the magnetic field is monopolar (well-like) or dipolar (not well-like).

(4) If determined to be monopolar, the exact position was located where the magnetic gradient was the highest and its respective location collected with the GNSS system.

(5) A wider 30+ meter circle was surveyed to rule out any additional weaker anomalous signatures in proximity to the target.

## FINDINGS

Upon completion of ground truthing all anomalies of interest were confirmed as non-O&G welllike. These targets were classified as structures, vehicles, culverts, steel debris piles, as well as 2 likely subsurface water wells (WW). No oil and gas well evidence was observed in the survey area including leaking petroleum liquids, gas or other contaminants. No other hazards were noted.

Note: All project magnetic maps, anomaly points and electronic files associated with this project are delivered separately and are not included in this project narrative.

## SUMMARY

UAVEX is pleased with the quality of data collected throughout this survey and the results of the ground truthing effort. Our flight and ground crews go to great lengths to ensure the highest quality of our surveys. This includes operating custom-tailored magnetic-survey UAV platforms, limiting data collection to periods of ideal environmental conditions and following strict flight operational procedures to ensure high target magnetic response.

UAVEX pioneered drone-based orphaned and abandoned well surveying. The techniques and methods utilized in this survey have resulted in having successfully located and mapped thousands of oil and gas wells across the US, serving industries such as utility-scale renewables, gas storage, environmental permitting, and commercial development projects.

## END OF REPORT



Please contact us with questions: UAV Exploration Inc. Renfrew, PA 724-432-2999 www.uavex.com

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